Towards Spatio-Temporal Reasoning in Description Logic f- $\mathcal{ALC}(D)$ -LTL

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With the emergence of fuzzy spatio-temporal knowledge, the representation and reasoning of fuzzy spatio-temporal knowledge have become one of the hot research issues in the fields of visual object tracking and GIS [1] [2]. Description logics (DLs), as a formal language of knowledge representation, have been widely used in the fields of computer science and artificial intelligence [3]. Hence, how to extend DLs to realize the representation and reasoning of fuzzy spatio-temporal knowledge needs to be solved.

In this work, we propose a fuzzy spatio-temporal description logic named f- $\mathcal{ALC}(D)$ -LTL that extends spatial fuzzy description logic f- $\mathcal{ALC}(D)$ [4] with linear temporal logic LTL [5]. In f- $\mathcal{ALC}(D)$ -LTL, vagueness is included through the standard Goedel semantics, space through a concrete domain of RCC-8 spacial operators, and time through a sequence of interpretations in the style of LTL connectives.

Let $\mathbf{C}, \mathbf{R}, \mathbf{T}, \mathbf{I}$ and \mathbf{O} be a disjoint set of concept names, abstract roles names, concrete roles names, abstract individual names and fuzzy spatial regions names. Also, let $R \in \mathbf{R}$ be an abstract role and $T \in \mathbf{T}$ be a concrete role, $\mathbf{d} \in \{C, DC, P, PP, EQ, O, DR, PO, EC, NTP, TPP, NTTP\}$ [6]. The f- $\mathcal{ALC}(D)$ -LTL atomic formulas ϕ are given by $\phi ::= \langle C_1 \sqsubseteq C_2 \bowtie n \rangle \mid \langle C_1(a) \bowtie n \rangle \mid$ $\langle R(a,b) \bowtie n \rangle \mid \langle T(a,o) \bowtie n \rangle \mid \langle \mathbf{d}(o_1,o_2) \bowtie n \rangle$ where $C_1, D_1 \in \mathbf{C}, R \in \mathbf{R}, T \in \mathbf{T}, a, b \in \mathbf{I}, o, o_1, o_2 \in \mathbf{O}, \bowtie \in \{\geq, >, <, \leq\}, n \in [0, 1]$. The f- $\mathcal{ALC}(D)$ -LTL formulas φ is the smallest set containing the atomic formulas such that: (i) if ϕ is an atomic formula, then ϕ is an f- $\mathcal{ALC}(D)$ -LTL formula; (ii) if φ_1, φ_2 are f- $\mathcal{ALC}(D)$ -LTL formulas, then so are $\neg \varphi_1, \circ \varphi_1, \varphi_1 \lor \varphi_2, \varphi_1 \land \varphi_2$ and $\varphi_1 U \varphi_2$, where temporal operators \circ and U mean that next and until, respectively. The semantic interpretation \mathcal{I} of f- $\mathcal{ALC}(D)$ -LTL can be defined as an infinite sequence $\mathcal{I}(0),$ $\mathcal{I}(1), \dots, \mathcal{I}(w)$ of fuzzy interpretations (see Fig. 1 for semantic interpretation).

Definition 1 (Truth). Given a temporal model $\mathfrak{M} = \langle \mathfrak{T}, \mathcal{I} \rangle$ and arbitrary time point (or state) $w \in W$. At time point w, the truth of f-ALC(D)-LTL formulas φ (denoted by $(\mathfrak{M}, w) \models \varphi$) is defined inductively as follows:

 $(\mathfrak{M}, w) \vDash \langle C_1 \sqsubseteq C_2 \bowtie n \rangle \quad iff \quad \inf f_{a \in \bigtriangleup^{\mathcal{I}}}(C_1^{\mathcal{I}(w)}(a) \Rightarrow C_2^{\mathcal{I}(w)}(a)) \\ (\mathfrak{M}, w) \vDash \langle C_1(a) \bowtie n \rangle \quad iff \quad C_1^{\mathcal{I}(w)}(a) \bowtie n$

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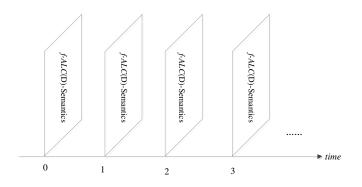


Fig. 1. A diagram of semantic interpretation of f- $\mathcal{ALC}(D)$ -LTL

 $\begin{aligned} (\mathfrak{M},w) &\vDash \langle R(a,b) \bowtie n \rangle \ iff \ R^{\mathcal{I}(w)}(a,b) \bowtie n \\ (\mathfrak{M},w) &\vDash \langle T(a,o) \bowtie n \rangle \ iff \ T^{\mathcal{I}(w)}(a,o) \bowtie n \\ (\mathfrak{M},w) &\vDash \langle \mathbf{d}(o_1,o_2) \bowtie n \rangle \ iff \ \mathbf{d}^{\mathcal{I}(w)}(o_1,o_2) \bowtie n \\ (\mathfrak{M},w) &\vDash \neg \varphi \ iff \ (\mathfrak{M},w) \nvDash \varphi \\ (\mathfrak{M},w) &\vDash \varphi_1 \lor \varphi_2 \ iff \ (\mathfrak{M},w) &\vDash \varphi_1 \lor (\mathfrak{M},w) \vDash \varphi_2 \\ (\mathfrak{M},w) &\vDash \varphi_1 \land \varphi_2 \ iff \ (\mathfrak{M},w) &\vDash \varphi_1 \land (\mathfrak{M},w) \vDash \varphi_2 \\ (\mathfrak{M},w) &\vDash \varphi_1 U \varphi_2 \ iff \ \exists v > w, \ \forall k \in (w, v) \ s.t \ (\mathfrak{M},v) \vDash \varphi_2 \ and \ (\mathfrak{M},k) \vDash \varphi_1 \end{aligned}$

Definition 2 (Satisfiability). Let $\mathfrak{M} = \langle \mathfrak{T}, \mathcal{I} \rangle$ be a temporal model. An f- $\mathcal{ALC}(D)$ -LTL formulas φ is satisfiable iff there is a temporal model \mathfrak{M} such that $(\mathfrak{M}, w_0) \vDash \varphi$, where $w_0 \in W$ is an initial state or an initial time point.

The satisfiability problem of $f - \mathcal{ALC}(D)$ -LTL formulas φ is a basic reasoning problem. Thus, we propose a tableau-based reasoning algorithm for determining satisfiability of $f - \mathcal{ALC}(D)$ -LTL formula. Our algorithm is based on the tableau algorithm for PLTL proposed by Wolper [7]. Similar to [8], our algorithm consists of two phases: (i) tableau construction, and (ii) tableau elimination. The first phase can obtain a complete tableau by applying a series of tableau rules for a given formula φ . The second phase can eliminate some unsatisfiable nodes of the complete tableau by repeatedly applying elimination rules. We also show the termination, soundness, and completeness of the tableau algorithm using Hintikka structure [9]. As a result, the satisfiability problem of $f - \mathcal{ALC}(D)$ -LTL formula φ is decidable.

Technical details and references to relevant work can be found in the full paper: Haitao Cheng, Zongmin Ma. $f-\mathcal{ALC}(D)$ -LTL: A Fuzzy Spatio-Temporal Description Logic, In Proceedings of the 10th International Conference on Knowledge Science, Engineering and Management(KSEM 2017), pages 93-105[10]. This work is supported by National Key R&D Program of China (No.2018YFB1003201), National Natural Science Foundation of China (No.61672296, No.61602261), Major Natural Science Research Projects in Colleges and Universities of Jiangsu Province (No. 18KJA520008), and NUPTSF(No.NY217133).

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