The Price of Anarchy of Affine Congestion Games with Similar Strategies

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Abstract. Affine congestion games are a well-studied model for selfish behavior in distributed systems, such as transportation and communication networks. Seminal influential papers in Algorithmic Game Theory have bounded the worst-case inefficiency of Nash equilibria, termed as price of anarchy, in several variants of these games. In this work, we investigate to what extent these bounds depend on the similarities among the players' strategies. Our notion of similarity is modeled by assuming that, given a parameter $\theta \geq 1$, the costs of any two strategies available to a same player, when evaluated in absence of congestion, are within a factor θ one from the other. It turns out that, for the non-atomic case, better bounds can always be obtained for any finite value of θ . For the atomic case, instead, $\theta < 3/2$ and $\theta < 2$ are necessary and sufficient conditions to obtain better bounds in games played on general graph topologies and on parallel link graphs, respectively. It is worth noticing that small values of θ model the behavioral attitude of players who are partially oblivious to congestion and are not willing to significantly deviate from what is their best strategy in absence of congestion.

1 Introduction

What route should I choose to go to work? This is a fundamental question that millions of people ask themselves daily, especially in metropolitan areas where the set of possible alternatives may be considerably diversified. In an ideal situation in which travel time is not affected by traffic, everyone would select the fastest path. However, when some roads become heavily congested, the ideal travel time may tremendously increase and some people may prefer taking longer detours to avoid traffic delay. As every worker can be seen as a selfish and rational agent who is only interested in minimizing its travel time, this type of problems gets suitably modeled as non-cooperative strategic games, usually called *routing games* [46].

There is a vast scientific literature on routing games, started from the beginning of the last century with the early works on transportation networks by Pigou [39], and developed and flourished later on, thanks to the advent of distributed networks, such as the Internet. One of the most successful and studied models in this area is that of *congestion games* [41] introduced by Rosenthal in 1973. In a congestion game, there is a finite set of players competing for a finite set of resources (i.e., roads in a network). Each player can choose an alternative from a set of available strategies, where each strategy is a subset of resources (i.e., one of the possible paths to go to work), and each resource has an associated latency function expressing the cost that a player incurs for using it; such a function only depends on the number of users (i.e., the travel time of a congested road as a function of the traffic). The cost of a player is defined as the sum of the latencies of the resources she chooses, and each player aims at minimizing it. A particularly well-studied case concerns *affine congestion games*, where the resource latency functions are affine (i.e., the travel time of a road increases linearly with its congestion).

Two versions of congestion games are usually considered in the literature depending on the amount of traffic controlled by the players: the atomic case and the non-atomic one. In the *atomic case* [41], every player controls a non-negligible amount of traffic (i.e., traffic is discrete and every player contributes for a congestion of one), while, in the *non-atomic case* [4,39], every player controls a negligible amount of traffic (i.e., traffic is a continuous flow and every player infinitesimally contributes to the congestion). A nice property possessed by congestion games is that they always admit pure Nash equilibria [38]: an outcome in which no player has an incentive to deviate to a different strategy.

The study of routing games (and so that of congestion games) has known a booming growth in the last twenty years thanks to the seminal papers by Koutsoupias and Papadimitriou [36] and Roughgarden and Tardos [47], which initiated the investigation of the inefficiency of pure Nash equilibria in noncooperative networks. The notion of price of anarchy [36], defined as the worstcase ratio of the social welfare of a pure Nash equilibrium to the social optimum, has been introduced to assess this phenomenon. Thanks to the effort of many researchers worldwide, we have a deep and almost complete understanding of the price of anarchy in (several variants of) congestion games [1, 3, 5, 6, 15, 16, 20, 26– 30, 32, 42, 44, 45, 47, 48]. In particular, the following results have been obtained with respect to affine congestion games. For the non-atomic case, Roughgarden and Tardos [47] showed that the price of anarchy is 4/3 and Roughgarden [42]complemented this result by proving that this value is independent of the network topology. For the atomic case, Awerbuch et al. [3] and Christodoulou and Koutsoupias [20] independently proved that the price of anarchy rises to 5/2, while Lücking et al. [37] showed, that for games played on parallel link graphs, i.e., for the case in which all players have the same strategic space and each strategy is a singleton set, the price of anarchy drops again to 4/3.

1.1 Our Contribution

In this work, we investigate to what extent the price of anarchy of affine congestion games is affected by the similarities among the players' strategies. Our notion of similarity is modeled by assuming that, given a parameter $\theta \geq 1$, the costs of any two strategies available to a same player, when evaluated in absence of congestion, are within a factor θ one from the other.

For the non-atomic case, we show that the price of anarchy is exactly $\frac{\left(\sqrt{\theta(\theta-1)}+\theta-2\right)^2}{\left(3\theta-4\right)\left(2\sqrt{\theta(\theta-1)}-\theta\right)}$ for any $\theta \in \mathbb{R}_{\geq 1} \setminus \left\{\frac{4}{3}\right\}$ and $\frac{9}{8}$ for $\theta = \frac{4}{3}$. Hence, improvements on the $\frac{4}{3}$ -bound shown by Roughgarden and Tardos [47] can be obtained for any finite value of θ . We also provide a lower bound of $\frac{4\theta}{3\theta+1}$ which holds for games played on parallel link graphs. For the atomic case, we show that the price of anarchy is exactly min $\left\{\frac{(4\theta-6)\sqrt{\theta^2-\theta+3}+4\theta^2+\theta-8}{8\theta-11}, \frac{5}{2}\right\}$ for $\theta \in \mathbb{R}_{\geq 1} \setminus \left\{\frac{11}{8}\right\}$ and $\frac{289}{120}$ for $\theta = \frac{11}{8}$, for games played on generic network topologies. For games played on parallel link graphs, instead, we show an upper bound of min $\left\{\frac{3\theta-2}{2\theta-1}, \frac{4}{3}\right\}$ and a lower bound of max $\left\{\frac{2\theta}{\theta+1}, \frac{4}{3}\right\}$, which are almost tight, since their difference is at most 0.0572. It turns out that $\theta < 3/2$ and $\theta < 2$ are necessary and sufficient conditions to obtain improved bounds in general games and in games played on parallel link networks, respectively. To this aim, we observe that small values of θ model the behavioral attitude of players who are partially oblivious to congestion and are not willing to significantly deviate from what is their best strategy in absence of congestion.

1.2 Related Work

The price of anarchy of non-atomic congestion games has been first considered in the seminal papers by Roughgarden and Tardos [47] and Roughgarden [42], and later on investigated in a number of follow-up papers [26–28]. The inefficiency of Nash equilibria in atomic congestion games has been first considered by Awerbuch et al. [3] and Christodoulou and Koutsoupias [20] who characterized the price of anarchy in games with affine latency functions. Caragiannis et al. [16] extended their bounds to singleton congestion games, where each strategy is a singleton set, while Lücking et al. [37] gave better bounds for games played on parallel link graphs. The price of anarchy has been largely studied for other classes of atomic congestion games (e.g. games with polynomial latencies [1, 23], or with general latency functions [5, 15, 32, 45], games with altruistic players [7, 9, 18, 19, 31, 40]). Furthermore, other quality metrics to measure the performance of atomic congestion games (e.g. the approximate price of anarchy [8, 23], the price of stability [2, 11, 21, 23], the approximation ratio of some special types of best-response dynamics [10, 15, 24, 50]) have been introduced and analyzed. Finally, mechanisms to improve the price of anarchy have been proposed in [13, 14, 17, 22, 25, 35, 32 - 34, 43, 49].

2 Model and Definitions

For an integer *i*, set $[i] := \{1, 2, ..., i\}$. An *atomic congestion game*, or simply congestion game, is a tuple $CG = ([n], E, (\ell_e)_{e \in E}, (\Sigma_i)_{i \in [n]})$, where [n] is a set of

 $n \geq 2$ players, E is a set of resources, $\ell_e : \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$ is the latency function of resource $e \in R$, and, for each player $i \in [n], \Sigma_i \subseteq 2^R \setminus \emptyset$ is her set of strategies (i.e. a strategy is a non-empty subset of resources).

A congestion game is affine when, for each $e \in E$, $\ell_e(x) = \alpha_e x + \beta_e$, with $\alpha_e, \beta_e \geq 0$. If $\beta_e = 0$ for any $e \in E$ we speak of linear congestion games. A singleton congestion game is a congestion game in which, for each $i \in [n]$ and $S \in \Sigma_i$, |S| = 1, i.e., each player can only select single resources, and a symmetric congestion game is one in which $\Sigma_i = \Sigma$ for each $i \in [n]$, i.e., all players share the same strategy space. Congestion games which are both symmetric and singleton are equivalently denoted as games played on parallel link graphs (in particular, when considering network games).

A strategy profile is an n-tuple of strategies $\boldsymbol{\sigma} = (\sigma_1, \ldots, \sigma_n)$, that is, a state of the game in which each player $i \in [n]$ is adopting strategy $\sigma_i \in \boldsymbol{\Sigma}_i$, so that $\times_{i \in [n]} \boldsymbol{\Sigma}_i$ denotes the set of strategy profiles which can be realized in CG. For a strategy profile $\boldsymbol{\sigma}$, the congestion of resource $e \in E$ in $\boldsymbol{\sigma}$, denoted as $k_e(\boldsymbol{\sigma}) := |\{i \in [n] : e \in \sigma_i\}|$, is the number of players using resource e in $\boldsymbol{\sigma}$.

The cost of player *i* in $\boldsymbol{\sigma}$ is defined as $c_i(\boldsymbol{\sigma}) := \sum_{e \in \sigma_i} \ell_e(k_e(\boldsymbol{\sigma}))$ and each player aims at minimizing it. For the sake of conciseness, when the strategy profile $\boldsymbol{\sigma}$ is clear from the context, we write k_e in place of $k_e(\boldsymbol{\sigma})$.

Congestion Games with Similar Strategies Given $\theta \ge 1$, a congestion game with θ -similar strategies is a congestion game $\mathsf{CG}(\theta)$ equal to a given congestion game CG , but where each player $i \in [n]$ has a strategy set $\Sigma_i(\theta) \subseteq \Sigma_i$ defined as follows: $\Sigma_i(\theta) := \{S \in \Sigma_i : \sum_{e \in S} \ell_e(1) \le \theta \sum_{e \in S'} \ell_e(1) \quad \forall S' \in \Sigma_i\}$, i.e. the costs of any two strategies available to a same player, when evaluated in absence of congestion (except for the unitary congestion due to herself), are within a factor θ one from the other. Observe that for $\theta = \infty$, $\mathsf{CG}(\theta)$ coincides with CG .

Pure Nash Equilibria Fix a strategy profile σ and a player $i \in [n]$. We denote with σ_{-i} the restriction of σ to all the players other than i; moreover, for a strategy $S \in \Sigma_i$, we denote with (σ_{-i}, S) the strategy profile obtained from σ when player i changes her strategy from σ_i to S, while the strategies of all the other players are kept fixed. A *pure Nash equilibrium* [38] is a strategy profile σ such that, for any player $i \in [n]$ and strategy $S \in \Sigma_i$, $c_i(\sigma) \leq c_i(\sigma_{-i}, S)$, that is, an outcome of the game in which no player can improve her situation by unilaterally deviating to another strategy.

Quality of Equilibria A social function that is usually used as a measure of the quality of a strategy profile in congestion games is the total latency, defined as $\mathsf{SUM}(\boldsymbol{\sigma}) := \sum_{i \in [n]} c_i(\boldsymbol{\sigma}) = \sum_{e \in E} k_e(\boldsymbol{\sigma}) \ell_e(k_e(\boldsymbol{\sigma}))$. A social optimum is a strategy profile $\boldsymbol{\sigma}^*$ minimizing SUM. Again, for the sake of conciseness, once a particular social optimum has been fixed, we write o_e to denote the value $k_e(\boldsymbol{\sigma}^*)$.

The price of anarchy of a congestion game CG (with respect to the social function SUM), denoted as PoA(CG), is the maximum of the ratio $SUM(\sigma)/SUM(\sigma^*)$, where σ is a pure Nash equilibrium for CG and σ^* is a social optimum for CG. The Price of Anarchy of Affine Congestion Games with Similar Strategies

Relatively to congestion games with θ -similar strategies, observe that the price of anarchy is a non decreasing function with respect to θ .

Remark 1. As shown in [6] for classic affine congestion games, given an affine congestion game with θ -similar strategies $CG(\theta)$, we have that there exists a linear congestion game with θ -similar strategies $CG^*(\theta)$ having the same price of anarchy of $CG(\theta)$ (a proof of this fact is deferred to the full version of this paper).

Non-atomic Congestion Games Non-atomic congestion games [39, 51, 4] are an important variant of atomic congestion games, obtained when the social impact of each player is infinitesimally small, and there are infinitely many players . A non-atomic congestion game, is a tuple NCG = $((f_i)_{i \in [n]}, E, (\ell_e)_{e \in E}, (\Sigma_i)_{i \in [n]})$ where $f_i \in \mathbb{R}_{\geq 0}$ is the amount of players of type *i* for any $i \in [n], \Sigma_i \subseteq 2^R \setminus \emptyset$ is the set of strategies for players of type *i* for any $i \in [n]$, and the other quantities are defined analogously to atomic congestion games.

The concepts defined for atomic congestion games can be adapted to the nonatomic case. A strategy profile is a tuple $\boldsymbol{\sigma} := (\sigma_{i,S})_{i \in [n], S \in \Sigma_i}$, that is a state of the game where $\sigma_{i,S} \geq 0$ is the total amount of players of type *i* selecting strategy *S*, for any $i \in [n]$ and $S \in \Sigma_i$. Given a strategy profile $\boldsymbol{\sigma}$, $k_e(\boldsymbol{\sigma}) :=$ $\sum_{i \in [n], S \in \Sigma_i: e \in S} \sigma_{i,S}$ is the total amount of players selecting *e* in $\boldsymbol{\sigma}$, and given a strategy *S*, $c_S(\boldsymbol{\sigma}) := \sum_{e \in S} \ell_e(k_e(\boldsymbol{\sigma}))$ is the cost of players selecting *S* in $\boldsymbol{\sigma}$.

A pure Nash equilibrium (often called Wardrop equilibrium [51] when referring to non-atomic games), is a strategy profile $\boldsymbol{\sigma}$ such that, for any $i \in [n]$ and $S \in \Sigma_i$ such that $\sigma_{i,S} > 0$, $c_S(\boldsymbol{\sigma}) \leq c_{S'}(\boldsymbol{\sigma})$ holds for any $S' \in \Sigma_i$. The total latency function is defined as $\mathsf{SUM}(\boldsymbol{\sigma}) := \sum_{i \in [n], S \in \Sigma_i} \sigma_{i,S} c_S(\boldsymbol{\sigma}) = \sum_{e \in E} k_e(\boldsymbol{\sigma}) \ell_e(k_e(\boldsymbol{\sigma}))$. Finally, the concepts of singleton games, symmetric games, social optima, and price of anarchy are defined as in atomic congestion games.

Given $\theta \geq 1$, a non-atomic congestion game with θ -similar strategy NCG(θ) is equal to a given non-atomic congestion game NCG, but where the set of strategy is $\Sigma_i(\theta) := \{S \in \Sigma_i : \sum_{e \in S} \ell_e(0) \leq \theta \sum_{e \in S'} \ell_e(0) \quad \forall S' \in \Sigma_i\}^3$.

3 Affine Congestion Games with Similar Strategies

In the following theorem we compute an upper bound on the price of anarchy of affine congestion games with θ -similar strategies for any $\theta \ge 1$, when there is no restrictions on the players' strategic space.

³ To define $\Sigma_i(\theta)$ for the non-atomic case, we consider $\ell_e(0)$ instead of $\ell_e(1)$ since, for non-atomic games, the contribution of each player to the congestion of each resource is null, differently from atomic games in which the contribution to the congestion is unitary.

Theorem 1 (Upper Bound). Let $CG(\theta)$ be an arbitrary affine congestion game with θ -similar strategies. Then⁴:

$$\mathsf{PoA}(\mathsf{CG}(\theta)) \le \begin{cases} \frac{(4\theta-6)\sqrt{\theta^2 - \theta + 3} + 4\theta^2 + \theta - 8}{8\theta - 11} & \text{if } 1 \le \theta < \frac{11}{8} \text{ or } \frac{11}{8} < \theta < \frac{3}{2} \\ \frac{289}{120} & \text{if } \theta = \frac{11}{8} \\ \frac{5}{2} & \text{if } \theta \ge \frac{3}{2} \end{cases}$$

Proof. If $\theta \geq \frac{3}{2}$ the upper bound of $\frac{5}{2}$ trivially holds since $\frac{5}{2}$ is the price of

anarchy of general affine congestion games [20, 3], i.e. for $\theta \to \infty$. Assume that $1 \leq \theta < \frac{11}{8}$ or $\frac{11}{8} < \theta < \frac{3}{2}$. Because of Remark 1, assume without loss of generality that $\mathsf{CG}(\theta)$ is a linear congestion game. Let $\boldsymbol{\sigma} =$ $(\sigma_1, \sigma_2, \ldots, \sigma_n)$ and $\sigma^* = (\sigma_1^*, \sigma_2^*, \ldots, \sigma_n^*)$ be a pure Nash equilibrium and a social optimum of $\mathsf{CG}(\theta)$, respectively. By applying the primal-dual method (a powerful technique introduced by Bilò [6] to determine good bounds on the performance of congestion games), we get the following linear program (recall that we write k_e and o_e in place of $k_e(\boldsymbol{\sigma})$ and $k_e(\boldsymbol{\sigma}^*)$, respectively):

$$\mathsf{LP}: \quad \max \quad \sum_{e \in E} \alpha_e k_e^2 \tag{1}$$

s.t.
$$\sum_{e \in E} \alpha_e k_e^2 \le \sum_{e \in E} \alpha_e o_e(k_e + 1)$$
(2)

$$\sum_{e \in E} \alpha_e k_e \le \theta \sum_{e \in E} \alpha_e o_e \tag{3}$$

$$\sum_{e \in E} \alpha_e o_e^2 = 1 \tag{4}$$

 $\alpha_e \ge 0, \quad \forall e \in E$

where:

- the objective function (1) is the total latency of σ ;
- (2) has been obtained by relaxing inequality $c_i(\sigma) \leq c_i(\sigma_{-i}, \sigma_i^*)$ (that holds because of the pure Nash equilibrium condition) to obtain inequalities of the form $\sum_{e \in \sigma_i} \alpha_e k_e \leq \sum_{e \in \sigma_i^*} \alpha_e (k_e + 1)$, and by summing them for any $i \in [n]$; • (3) has been obtained by summing all the inequalities $\sum_{e \in \sigma_i} \alpha_e \leq 1$
- $\theta \sum_{e \in \sigma_i^*} \alpha_e$ for each $i \in [n]$ (holding since strategies are θ -similar);
- the linear coefficients α_e 's are the variables of the linear program, and the other quantities are fixed parameters;
- (4) normalizes the optimal social function, so that the maximum value of the objective function is an upper bound on the price of anarchy.

By taking the dual of LP, in which we associate the dual variable $x(\theta)$ to the primal constraint (2), the dual variable $y(\theta)$ to the primal constraint (3), and

⁴ We consider separately the case $\theta = \frac{11}{8}$ since the function determining the price of anarchy for the cases $1 \le \theta < \frac{11}{8}$ or $\frac{11}{8} < \theta < \frac{3}{2}$ (so as other functions considered in the proof) is not defined for $\theta = \frac{11}{8}$ (it is of the form $\frac{0}{0}$), but can be extended by continuity to $\theta = \frac{11}{8}$, thus obtaining for $\theta \to \frac{11}{8}$ a price of anarchy of $\frac{289}{120}$.

the dual variable $\gamma(\theta)$ to the primal constraint (4), we get:

DLP: min
$$\gamma(\theta)$$

s.t. $\gamma(\theta)o_e^2 - k_e^2 - x(\theta)\left(-k_e^2 + o_e(k_e+1)\right) - y(\theta)\left(-k_e + \theta o_e\right) \ge 0, \forall e \in E$ (5)
 $x(\theta), y(\theta) \ge 0$

For the weak duality theorem, we get that any feasible solution $(\gamma(\theta), x(\theta), y(\theta))$ of DLP is such that $\gamma(\theta)$ is an upper bound on the maximum value of LP, i.e. an upper bound on the price of anarchy. One can show that, by setting $\gamma(\theta) := \frac{(4\theta-6)\sqrt{\theta^2-\theta+3}+4\theta^2+\theta-8}{8\theta-11}, x(\theta) := \frac{10\theta-10-2\sqrt{\theta^2-\theta+3}}{8\theta-11} \ge 1$ and $y(\theta) := \frac{4\sqrt{\theta^2-\theta+3}+4\theta-13}{8\theta-11} \ge 0$, constraint (5) is verified for any $k_e, o_e \in \mathbb{Z}_{\ge 0}$ (a formal proof of this fact is deferred to the full version), and the claim follows.

Finally, if $\theta = \frac{11}{8}$ it suffices considering the quantities $\gamma(\theta), x(\theta), y(\theta)$ defined above, but for $\theta \to \frac{11}{8}$, and the claim follows as well.

We have that the upper bound shown in Theorem 1 is tight (the proof is deferred to the full version).

Theorem 2 (Lower Bound). For any $\epsilon > 0$, there exists an affine congestion game with θ -similar strategies $CG(\theta)$ such that:

$$\mathsf{PoA}(\mathsf{CG}(\theta)) \geq \begin{cases} \frac{(4\theta-6)\sqrt{\theta^2 - \theta + 3} + 4\theta^2 + \theta - 8}{8\theta - 11} - \epsilon & \text{if } 1 \le \theta < \frac{11}{8} \text{ or } \frac{11}{8} < \theta < \frac{3}{2} \\ \frac{289}{120} - \epsilon & \text{if } \theta = \frac{11}{8} \\ \frac{5}{2} & \text{if } \theta \ge \frac{3}{2} \end{cases}$$

3.1 The Case of Symmetric Singleton Games

Now, we focus on the case of symmetric singleton games. In the following theorem, we compute an upper bound on the price of anarchy of affine symmetric singleton congestion games with θ -similar strategies, for any $\theta \geq 1$.

Theorem 3 (Upper Bound). Let $CG(\theta)$ be an arbitrary affine symmetric singleton congestion game with θ -similar strategies. Then:

$$\mathsf{PoA}(\mathsf{CG}(\theta)) \leq \begin{cases} \frac{3\theta-2}{2\theta-1} & \text{ if } 1 \le \theta < 2\\ \frac{4}{3} & \text{ if } \theta \ge 2 \end{cases}$$

Proof. If $\theta \geq 2$ the upper bound of $\frac{4}{3}$ trivially holds since $\frac{4}{3}$ is the price of anarchy of affine symmetric singleton games, i.e. when $\theta = \infty$.

Assume that $\theta \in [1, 2)$. Let $\boldsymbol{\sigma} := (\sigma_1, \sigma_2, \dots, \sigma_n)$ and $\boldsymbol{\sigma}^* := (\sigma_1^*, \sigma_2^*, \dots, \sigma_n^*)$ be a pure Nash equilibrium and a social optimum of $\mathsf{CG}(\theta)$, respectively. The discrepancy of resource $e \in E$ is defined as $d_e := k_e - o_e$. Resource e is overloaded if $d_e > 0$; it is underloaded if $d_e < 0$. Define $E^+ := \{e \in E : d_e > 0\}$ as the set of overloaded resources and $E^- := \{e \in E : d_e < 0\}$ as the set of underloaded ones. Note that, since in any strategy profile each player uses exactly one resource, the following property holds: $\sum_{e \in E^+} d_e + \sum_{e \in E^-} d_e = 0$. Define the discrepancy between $\boldsymbol{\sigma}$ and $\boldsymbol{\sigma}^*$ as the value $d = \sum_{e \in E^+} d_e$.

A rebalancing deviation is a deviation (σ_{-i}, s_i) such that $\sigma_i \in E^+$ and $s_i \in E^-$, that is, the deviating player abandons an overloaded resource to join an underloaded one; hence, a rebalancing deviation can be specified by a triple (p, old, new), where $p \in N$ is the deviating player, $\text{old} \in E^+$ is the abandoned resource and $\text{new} \in E^-$ is the newly joined one. A rebalancing is a collection of rebalancing deviations in which each player is involved at most once. It is easy to see that there exists a rebalancing $(p(i), \text{old}(i), \text{new}(i))_{i \in [d]}$ made up of d rebalancing deviations which recreates σ^* starting from σ . Since σ is a Nash equilibrium, for each $i \in [d]$, we have $\alpha_{\text{old}(i)}k_{\text{old}(i)} + \beta_{\text{old}(i)} \leq \alpha_{\text{new}(i)}(k_{\text{new}(i)} + 1) + \beta_{\text{new}(i)}$. Moreover, since $CG(\theta)$ is a symmetric singleton game with θ -similar strategies, for each $i \in [d]$, we have $\alpha_{\text{new}(i)} + \beta_{\text{new}(i)} \leq \theta \left(\alpha_{\text{old}(i)} + \beta_{\text{old}(i)}\right)$. Hence, by applying the primal-dual method, we get the following linear program:

$$\begin{split} \mathsf{LP}: & \max \quad \sum_{e \in E} \alpha_e k_e^2 + \beta_e k_e \\ & \text{s.t.} \quad \alpha_{\mathsf{old}(i)} k_{\mathsf{old}(i)} + \beta_{\mathsf{old}(i)} \leq \alpha_{\mathsf{new}(i)} (k_{\mathsf{new}(i)} + 1) + \beta_{\mathsf{new}(i)}, \quad \forall i \in [d] \\ & \alpha_{\mathsf{new}(i)} + \beta_{\mathsf{new}(i)} \leq \theta \left(\alpha_{\mathsf{old}(i)} + \beta_{\mathsf{old}(i)} \right), \quad \forall i \in [d] \\ & \sum_{e \in E} \alpha_e o_e^2 + \beta_e o_e = 1, \qquad \alpha_e, \beta_e \geq 0 \quad \forall e \in E \end{split}$$

By taking the dual of LP, in which we associate the dual variable $x_i(\theta)$ to the *i*th primal constraint of the first family, the dual variable $y_i(\theta)$ to the *i*th primal constraint of the second family, and the dual variable $\gamma(\theta)$ to the last primal constraint, we get:

One can show that, by setting $\gamma(\theta) := \frac{3\theta-2}{2\theta-1}$, $x_i(\theta) := \frac{3\theta-1}{2\theta-1} \ge 1$ and $y_i(\theta) := \frac{1}{2\theta-1} \ge 0 \quad \forall i \in [d]$, both dual constraints are verified for any $k_e, o_e \in \mathbb{Z}_{\ge 0}$ (a formal proof of this fact is deferred to the full version), thus, for the weak duality theorem, the considered $\gamma(\theta)$ is an upper bound on $\mathsf{PoA}(\mathsf{CG}(\theta))$.

In the following theorem, we show that the previous upper bound is almost tight, by exhibiting an almost tight lower bound.

Theorem 4 (Lower Bound). For any $\theta \ge 1$, there exists an affine symmetric singleton congestion game with θ -similar strategies $CG(\theta)$, such that:

$$\mathsf{PoA}(\mathsf{CG}(\theta)) \geq \begin{cases} \frac{2\theta}{\theta+1} & \text{ if } 1 \le \theta < 2\\ \frac{4}{3} & \text{ if } \theta \ge 2 \end{cases}$$

Proof. For $\theta \geq 2$ the lower bound defined in [37] is an affine symmetric singleton congestion game with θ -similar strategies and having a price of anarchy of $\frac{4}{3}$. If $\theta < 2$, consider a symmetric singleton congestion game CG having two players, two resources e_1, e_2 with $\ell_{e_1}(x) := (\theta - 1)x + 2 - \theta$ and $\ell_{e_2}(x) := \theta$. One can easily observe that the strategy profile σ in which all players select resource e_1 is a pure Nash equilibrium, and that both strategies $\{e_1\}$ and $\{e_2\}$ belong to $\Sigma(\theta)$. Let σ^* be the strategy profile in which one player selects e_1 , and the other one selects e_2 . We get $\text{PoA}(\text{CG}(\theta)) \geq \frac{\text{SUM}(\sigma)}{\text{SUM}(\sigma^*)} = \frac{((\theta - 1)2 + 2 - \theta)2}{((\theta - 1) + (2 - \theta) + \theta} = \frac{2\theta}{1 + \theta}$.

4 Affine Non-atomic Congestion Games with Similar Strategies

Now, we compute an upper bound on the price of anarchy of non-atomic congestion games with θ -similar strategies, for any $\theta \geq 1$ (a formal proof is deferred to the full version).

Theorem 5 (Upper Bound). Let NCG(θ) be an arbitrary affine non-atomic congestion game with θ -similar strategies. Then:

$$\mathsf{PoA}(\mathsf{CG}(\theta)) \leq \begin{cases} \frac{\left(\sqrt{(\theta-1)\theta} + \theta - 2\right)^2}{(3\theta-4)\left(2\sqrt{(\theta-1)\theta} - \theta\right)} & \text{if } 1 \leq \theta < \frac{4}{3} \text{ or } \frac{4}{3} < \theta \\ \frac{9}{8} & \text{if } \theta = \frac{4}{3} \end{cases}$$

We show that the previous upper bound is tight (a formal proof is deferred to the full version).

Theorem 6 (Lower Bound). For any $\theta \ge 1$ and for any $\epsilon > 0$, there exists an affine non-atomic congestion game with θ -similar strategies NCG(θ) such that:

$$\mathsf{PoA}(\mathsf{CG}(\theta)) \geq \begin{cases} \frac{\left(\sqrt{(\theta-1)\theta} + \theta - 2\right)^2}{(3\theta-4)\left(2\sqrt{(\theta-1)\theta} - \theta\right)} - \epsilon & \text{if } 1 \leq \theta < \frac{4}{3} \text{ or } \frac{4}{3} < \theta \\ \frac{9}{8} - \epsilon & \text{if } \theta = \frac{4}{3} \end{cases}$$

We also exhibit an almost tight lower bound for affine symmetric singleton nonatomic congestion games.

Theorem 7 (Lower Bound for Symmetric Singleton Games). For any $\theta \ge 1$, there exists an affine symmetric singleton non-atomic congestion game with θ -similar strategies NCG(θ), such that:

$$\mathsf{PoA}(\mathsf{NCG}(\theta)) \geq \frac{4\theta}{3\theta+1}$$

Proof. Consider a symmetric singleton non-atomic congestion game NCG having a unitary amount of players, and two resources e_1, e_2 with $\ell_{e_1}(x) := (\theta - 1)x + 1$ and $\ell_{e_2}(x) := \theta$. One can easily observe that the strategy profile σ in which all players select resource e_1 is a pure Nash equilibrium, and that both strategies $\{e_1\}$ and $\{e_2\}$ belong to $\Sigma(\theta)$. Let σ^* be the strategy profile in which half of the players select e_1 , and the remaining ones select e_2 . We get $\text{PoA}(\text{NCG}(\theta)) \geq \frac{\text{SUM}(\sigma)}{\text{SUM}(\sigma^*)} = \frac{(\theta - 1) + 1}{\frac{1}{4}(\theta - 1) + \frac{1}{2} + \frac{1}{2}\theta} = \frac{4\theta}{3\theta + 1}$.

5 Conclusions and Open Problems

In this work we have introduced the class of congestion games with similar strategies, and we have almost completely characterized the performance of such games in terms of price of anarchy. Our work leaves several open problems. For instance, when considering symmetric singleton games, the given upper and lower bounds are not tight for both the atomic and the non-atomic case. Moreover, it would be interesting considering more general latency functions (e.g. polynomial).

Overall, despite its theoretical importance, we think that our parametrization may provide an interesting and reasonable step towards the definition of a more concrete model for selfish routing games.

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The Price of Anarchy of Affine Congestion Games with Similar Strategies

11

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- 12 V. Bilò and C. Vinci
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